

# Inter- and Intra-Subject Variations in Activity Recognition Using Inertial Sensors and Magnetometers



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## Introduction

- human activity recognition through the use of sensor units containing accelerometers, gyros, and magnetometers
- investigate the effect of inter- and intra-personal differences on classification performance
- the acquired data varies nonlinearly from subject to subject in terms of amplitude & speed
- hard to classify activities of a person using another person's data
- lower classification performance in subject-based leave-one-out (L10) compared to  $P$ -fold cross validation

## Dataset

The dataset for activity recognition [1] is used:

- 8 subjects performing 19 activities, 5 min each
- 5 sensor units containing uncalibrated tri-axial accelerometers, gyros, and magnetometers (9 axes/unit) sampled at 25 Hz

## Segmentation and Feature Extraction

- Data is segmented into 5-sec segments:
  - 60 segments per activity of a subject
- A 1,170-element feature vector is calculated from each segment (corresponding to all sensors and units) [1].
- Each signal is made zero-mean.
- Both raw and zero-mean signals, as well as the feature vectors, are used comparatively.

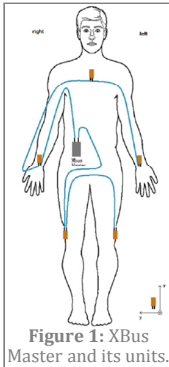


Figure 1: XBus Master and its units.

## Identifying the "Best" Subjects

- The "best" subject is the one whose data are the most similar to other subjects on average
- For each subject, the distances from all signals of that subject to all other subjects are averaged out in terms of the 3 distance measures.
- Both raw and zero-mean time-domain signals, and feature vectors are used in the comparison.

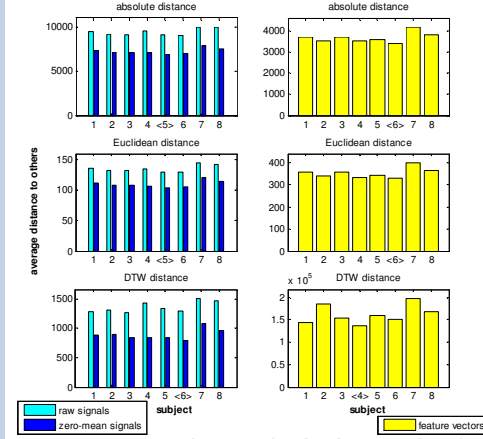


Figure 2: Average distance of each subject to others.\*

## Average Intra-Subject Distance per Activity

- For each activity, the amount of variation in the data with respect to subjects is calculated.
- Distances between all distinct subject pairs are calculated and averaged out.
- The 3 distance measures are applied to both raw and zero-mean time-domain signals.

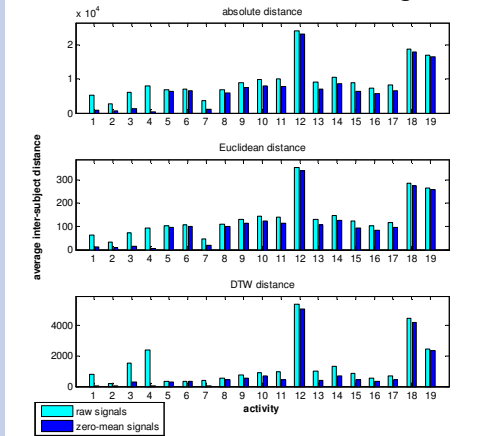


Figure 3: Average intra-subject distance per activity.\*

## Average Mean and Std. of Inter-Activity Distances

- Distances between time-domain signals (of all the subjects, units, and sensors) belonging to one activity and time-domain signals (of the corresponding subjects, units, and sensors) belonging to another activity are calculated and averaged out for each subject, unit, and sensor separately.
- Only zero-mean signals are used.

## Inter-Activity Distances per Subject

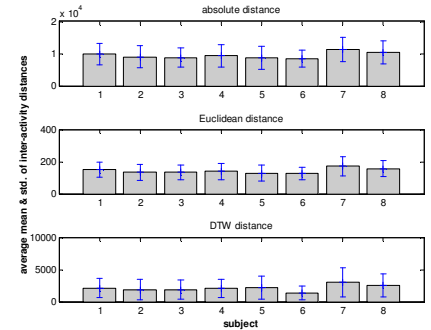


Figure 4: Average inter-activity distance per subject.\*

## Inter-Activity Distances per Unit Location

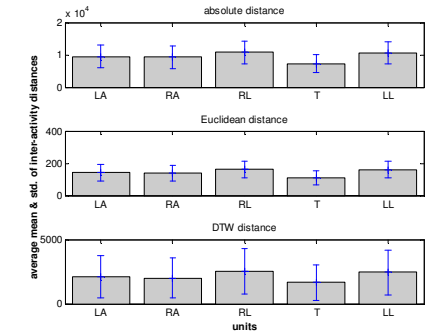


Figure 5: Average inter-activity distance per unit.\*

## Inter-Activity Distances per Sensor Type

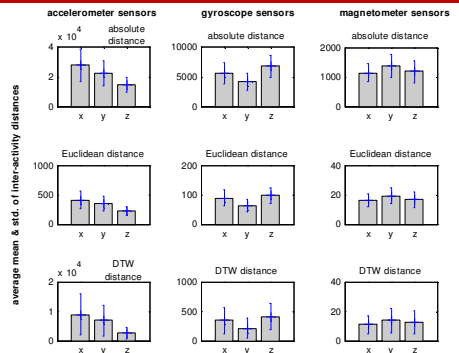


Figure 6: Average inter-activity distance per sensor.\*

## Distance Measures

3 different distance measures are used to compare the signals  $x[n]$  and  $y[n]$  ( $1 \leq n \leq N$ ):

- **absolute distance:**

$$d_{\text{abs}}(x[n], y[n]) = \sum_{n=1}^N |x[n] - y[n]|$$

- **Euclidean distance:**

$$d_{\text{Eucl}}(x[n], y[n]) = \sqrt{\sum_{n=1}^N (x[n] - y[n])^2}$$

- **Dynamic Time-Warping (DTW) distance:**

$$d_{\text{DTW}}(x[n], y[n])$$

## Effect of Bias Error

If  $y[n] = x[n] + b$  with  $b$  being the bias error, if  $N = 100$  and  $b = 0.01$

$$d_{\text{abs}}(x[n], y[n]) = Nb = 1$$

$$d_{\text{Eucl}}(x[n], y[n]) = \sqrt{Nb} = 0.1$$

$$d_{\text{DTW}}(x[n], y[n]) \leq Nb \leq 1$$

## Conclusion

- The "best" subject may not always be the one performing activities the best.
- Removing mean values highly affects the results due to bias errors.
- Comparison based on time-domain signals can be misleading in "random" activities.

## Acknowledgments

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## References

- [1] K. Altun, B. Barshan, and O. Tunçel, "Comparative study on classifying human activities with miniature and inertial sensors," *Pattern Recognition*, 43(10):3605–3620, Oct. 2010.

\* Only 5% of the data is used in the DTW case to speed up the computations. To reduce the data used, all time-domain signals are cropped from the end and only the first 3 feature vectors are used.