## EEE 424 Final

## January 10, 2014

Duration: 150 minutes.

Examination is CLOSED-BOOK and CLOSED-NOTES. Do NOT use CALCULATOR.

NO CREDIT will be given for ANSWERS without PROPER JUSTIFICATION.

NAME: \_\_\_\_\_

ID NUMBER: \_\_\_\_\_

SIGNATURE: \_\_\_\_\_

You may or may not need the following formulas:

$$\begin{aligned} \cos \theta &= \frac{1}{2} \left( e^{j\theta} + e^{-j\theta} \right) & \sin \theta &= \frac{1}{21} \left( e^{j\theta} - e^{-j\theta} \right) & \sum_{k=M}^{N} \alpha^{k} &= \frac{\alpha^{M} - \alpha^{N+1}}{1 - \alpha} \\ \cos^{2} \theta &= \frac{1}{2} (1 + \cos 2\theta) & \sin^{2} \theta + \cos^{2} \theta = 1 & \sum_{k=M}^{N} \alpha^{k} &= \frac{\alpha^{M} - \alpha^{N+1}}{1 - \alpha} \\ \end{aligned}$$

$$\begin{aligned} & \text{Continuous-Time} \\ \text{Fourier Series} & x(t) &= \sum_{k=\infty}^{\infty} a_{k} e^{\beta w_{0}t}, \omega_{0} &= \frac{2\pi}{T_{0}} \\ & a_{k} &= \frac{1}{T_{0}} \int_{\tau_{k=\infty}}^{\infty} x(t) e^{-\beta w_{0}} dt \\ & X(w) &= \sum_{k=\infty}^{\infty} 2\pi a_{k} \delta(\omega - k\omega_{0}) \\ \end{aligned}$$

$$\begin{aligned} & \text{Continuous-Time} \\ \text{Fourier Transform} & x(t) &= \frac{1}{2\pi} \int_{\infty}^{\infty} x(t) e^{-\beta w_{1}} dw \\ & X(w) &= \int_{\infty}^{\infty} x(t) e^{-\beta w_{1}} dt \\ \end{aligned}$$

$$\begin{aligned} & \text{Discrete-Time} \\ \text{Fourier Series} & x[n] &= \sum_{k=\infty}^{\infty} x_{k} a_{k} e^{j\frac{2\pi}{N}w_{0}} \\ & x(\theta) &= \sum_{k=\infty}^{\infty} 2\pi a_{k} \delta(\theta - \frac{2\pi}{N}k); a_{k+N} = a_{k} \\ \end{aligned}$$

$$\begin{aligned} & \text{Discrete-Time} \\ \text{Fourier Transform} & x[n] &= \frac{1}{2\pi} \int_{\tau_{n}}^{X} x(\theta) e^{j\theta w} d\theta \\ & x(\theta) &= \sum_{k=\infty}^{\infty} x[n] e^{-j\theta w} \\ \end{aligned}$$

$$\begin{aligned} & x(\theta) &= \sum_{k=\infty}^{\infty} x[n] e^{-j\theta w} \\ x(\theta) &= \sum_{k=\infty}^$$

## PROBLEM 1: (25 points) No credit will be given to answers without proper justification.

a) (5 Points) Given that  $x[n] = \{4,3,2,1,0\} \xleftarrow{DFT,5} X[k]$  $s[n] = \{0,1,0,0,1\} \xleftarrow{DFT,5} S[k]$ 

Determine y[n], which yields Y[k]=X[k]S[k] where Y[k] is 5 point DFT of y[n].

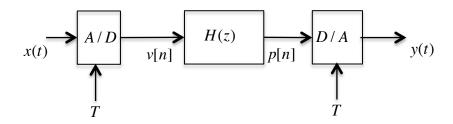
b) Evaluate the DTFT of the following in terms of the DTFT of x[n].(10 Points)

a. 
$$x_1[n] = \begin{cases} x[n], \text{ if } n \text{ is odd,} \\ 0, \text{ otherwise.} \end{cases}$$
  
b.  $x_2[n] = x[n]x[-n]$   
c.  $x_3[n] = \frac{x[n]}{(-1)^n}$ 

c) Given that  $x[n] = 0.5^n u[n]$  and  $X(e^{jw})$  is the DTFT of x[n].

Define  $Y[k] = X\left(e^{j\frac{2\pi}{10}k}\right), k = 0, 1, ..., 9$ . Construct the sequence y[n] that is the length-10 IDFT of Y[k]. Provide y[n] in a closed form (if possible). (10 points)

PROBLEM 2: (25 points) No credit will be given to answers without proper justification.



The digital filter H(z) is casual and described by

y[n] = (1/2)y[n-1] + (1/2)x[n] + (1/2)x[n-1].

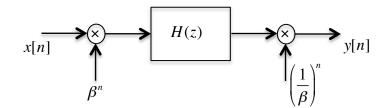
**a**) What is the kind of H(z), i.e., FIR or IIR? LPF or HPF? Linear phase? Minimum phase? (5 Points)

- **b**) What is the 3dB bandwidth of H(z)? (5 Points)
- c) What is p[n] if  $v[n] = 2\sin(\pi n/3 + \pi/4)$ ? (5 Points)

d) Given that A/D and D/A converters are ideal and use anti-alising filters with cut off  $\pi/T$ .

What is the frequency response of the analog filter from x(t) to y(t)? (10 Points)

PROBLEM 3: (25 points) No credit will be given to answers without proper justification.

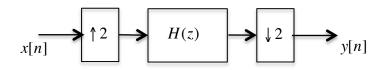


Given that x[n] is the input and y[n] is the output to the overall system, and

$$H(z) = \frac{1}{1 - (1/3)z^{-1}}$$
 is a casual LTI filter.

- a) Is the overall system linear? Is the overall system time invariant? (5 Points)
- **b**) What is Y(z) in terms of X(z)? What is the ROC of Y(z) in terms of X(z). (5 Points)
- c) What is y[n] given that  $x[n] = \delta[n-1]$ ? (5 Points)
- d) Given that  $x[n] = 2\sin(2\pi n/3 + \pi/4)$  and  $\beta = e^{j(\pi/8)n}$ , what is the output y[n]? (10 Points)

## PROBLEM 4: (25 points) No credit will be given to answers without proper justification.



Given the input is x[n], the output is y[n] and H(.) is LTI.

- a) Is the overall system linear? Is the overall system time invariant? (5 Points)
- b) What is Y(z) in terms of X(z)? (5 Points)
- c) Under what conditions x[n]=y[n]? (5 Points)
- d) Given that  $h[n] = \delta[n] + \delta[n-1] + \delta[n-2]$ , can you derive the polyphase representation where the decimators are in the front and interpolators are at the end? (10 Points)